

**OPTIMAL CONTROL OF HYBRID VEHICLES (ADVANCES  
IN INDUSTRIAL CONTROL)**

**Alissa Files**

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Hybrid Electric Vehicles; Automotive 3: This requirement effectively dictates that disturbances should be attenuated as they propagate along the platoon of following vehicles. Inspired by the geometry of sliding mode control, this paper proposes a new control strategy for this problem.

The stability of the closed loop system under the proposed steering scheme is The inputs are the state variables collected by the sensors, and the outputs are the control variables calculated by the control algorithm. A unique characteristic of the proposed model is that it is built to ensure structural parsimony while retaining physiological transparency.

Finally, based on this trade-off the supervisory control strategy relying on proposed multi-input strategy is able to manage engine limits effectively and offers better transient response than the traditional min-max architecture with linear regulators.